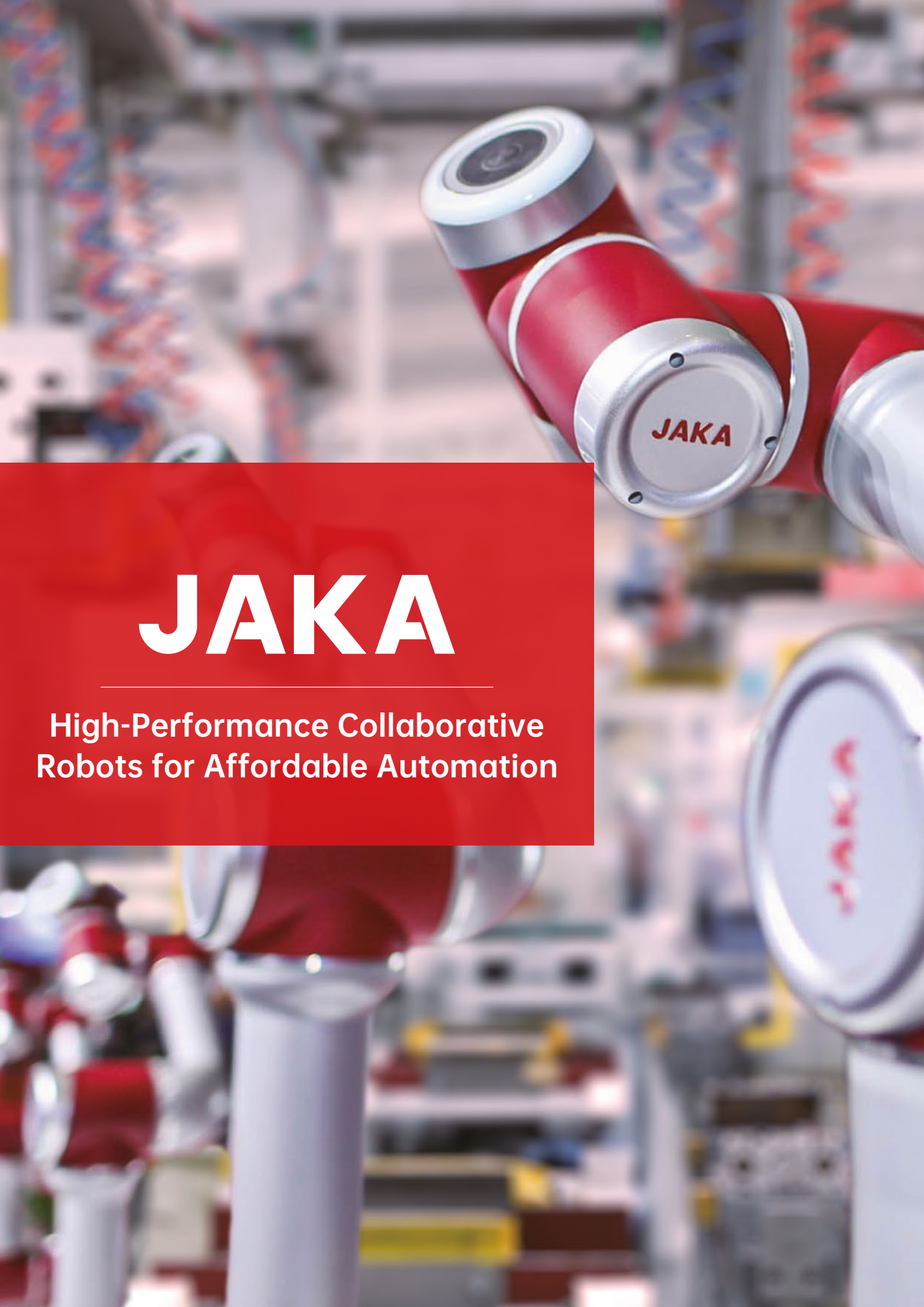


A red and white JAKA collaborative robot arm is shown in a factory setting. The arm is positioned diagonally across the frame, with its end effector pointing towards the top right. The background is a blurred industrial environment with various mechanical components and wiring. A red banner is overlaid on the left side of the image, containing the JAKA logo and tagline.

JAKA

High-Performance Collaborative
Robots for Affordable Automation



2014

- >>> JAKA Robotics is founded as a spin-off of the Robotics Institute of Shanghai Jiao Tong University, established in 1979.

2016

- >>> JAKA establishes a manufacturing base in Changzhou and an R&D centre in Shanghai.
- >>> Recognized as a National High-Tech Enterprise by China's Ministry of Science and Technology.
- >>> Series A funding completed.

2017

- >>> Launch of JAKA Zu collaborative robots.

2018

- >>> Recognized in automotive, 3C, and general industries servicing over 1,500 customers.
- >>> JAKA+ cobots ecosystem platform established.
- >>> Series A+ funding completed.

2019

- >> JAKA becomes a global company with over 200 international customers.
- >> JAKA establishes strategic partnerships with leading automotive and electronics companies.
- >>> Recognized as a "Technology Giant" by the Science and Technology Commission of Shanghai Municipality.
- >>> JAKA opens its Shenzhen office.
- >>> Series B funding completed.

2020

- >> JAKA opens its R&D centre in Japan.
- >> Series C funding completed.

2022

- >>> Global expansion begins with investment in a sales team for international markets.
- >>> JAKA opens its European headquarters in Germany.

JAKA

Product Matrix



Ease of Use



Safety



Reliability



Compatibility



JAKA S Series



JAKA Pro Series



JAKA Zu Series



JAKA Mini Series



JAKA Lens 2D



JAKA Vision Protection System

Flexible • Intelligent

Adapting to various application scenarios
to meet the needs of all industries



No Teach Pendant

Operating JAKA collaborative robots does not require a traditional teach pendant. It can be easily carried out via a tablet, smartphone, or PC, offering great flexibility.



Wireless Connection

With wireless connectivity, communicating with and assigning tasks to a cobot is effortless. No more wires! Enjoy a cleaner, safer workspace with JAKA cobots.



Safe Human-Robot Collaboration

JAKA cobots are designed for safe interactions with humans – no safety fence required – thanks to collision detection, enabled by a built-in torque feedback module. Users can adjust flexibility, so that even the lightest bump will cause the cobot to stop, preventing harm.



Graphical Programming

Program effortlessly on any graphical device – PC, tablet, or phone. The intuitive software requires no prior programming experience, allowing anyone to easily set and adjust positions and tasks.



Drag Teaching

Users and integrators can deploy a cobot in minutes using drag teaching. Simply move the cobot to any position, and it will instantly memorize it.



Plug-and-Play

A few minutes is all it takes to install JAKA cobots. Whether on a horizontal or a vertical surface, they are easy to mount and ready to go. Flexible and lightweight, the cobots are compatible with a wide range of grippers and end effectors. This plug-and-play design allows users to quickly deploy and re-deploy in any production environment.

JAKA Zu Series


Simplified

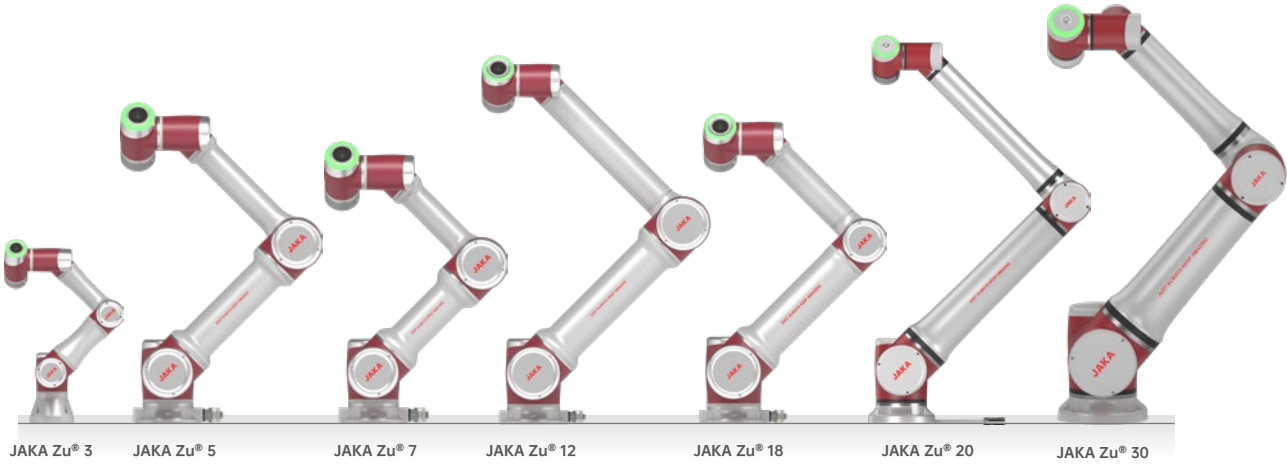
Plug and play setup, convenient deployment, flexible production.


Intelligent

Flexible, intelligent, easy to operate, and efficient in collaboration.


Specialized

Built for reliable performance in various high-precision collaborative tasks.



JAKA S Series


Highly Sensitive

Optimized drag teaching for superior precision and control.


User-Friendly

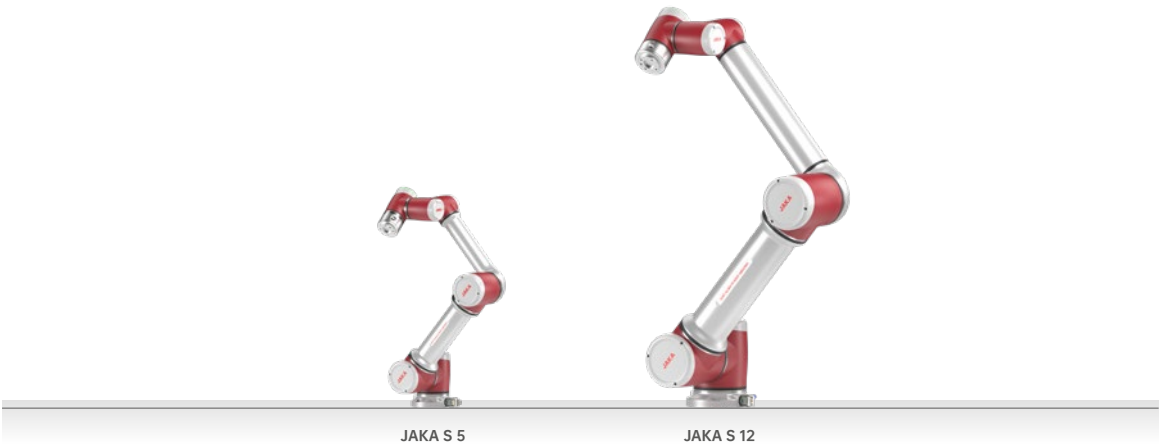
Simple app setup with real-time force value display.


Practical

Multiple force control modes with consistent force accuracy.


Safe

Full-arm collision detection self-learning monitoring.



JAKA Pro Series


Exceptional Durability

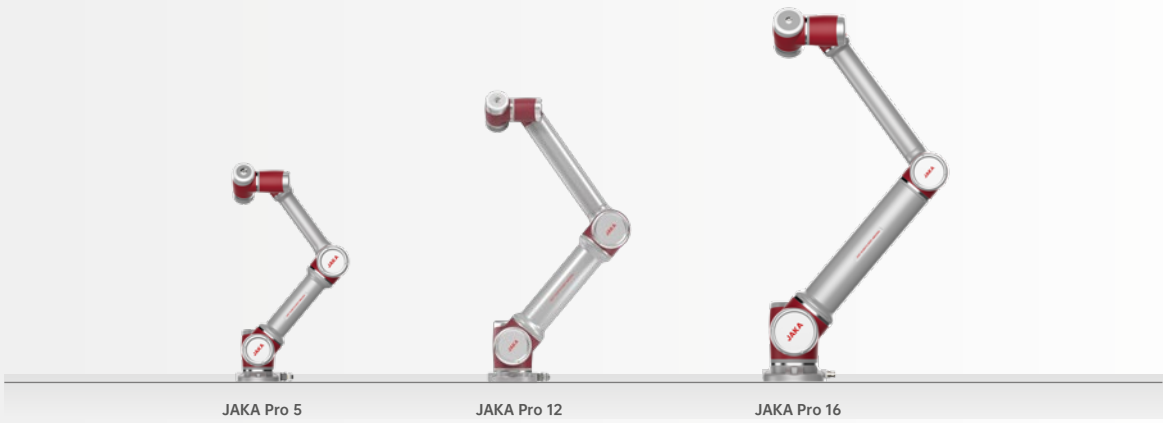
Industry's highest IP68 protection level - fully resistant to oil and dust.


Reduced Maintenance

High-precision, low-maintenance design for worry-free production.


Enhanced Efficiency

Fast, intelligent operation with seamless and safe integration.



JAKA Mini Series


Business-Ready

Compact, low-noise design. Ideal for hospitality, education, retail, and services.


Lightweight

Weighing under 10 kg, it offers exceptional portability and convenience.


Cost-Effective

Helps achieve high-quality results with a low initial investment.



JAKA Zu



Ease of Integration

Plug-and-play,
easy deployment,
with a compact
footprint.



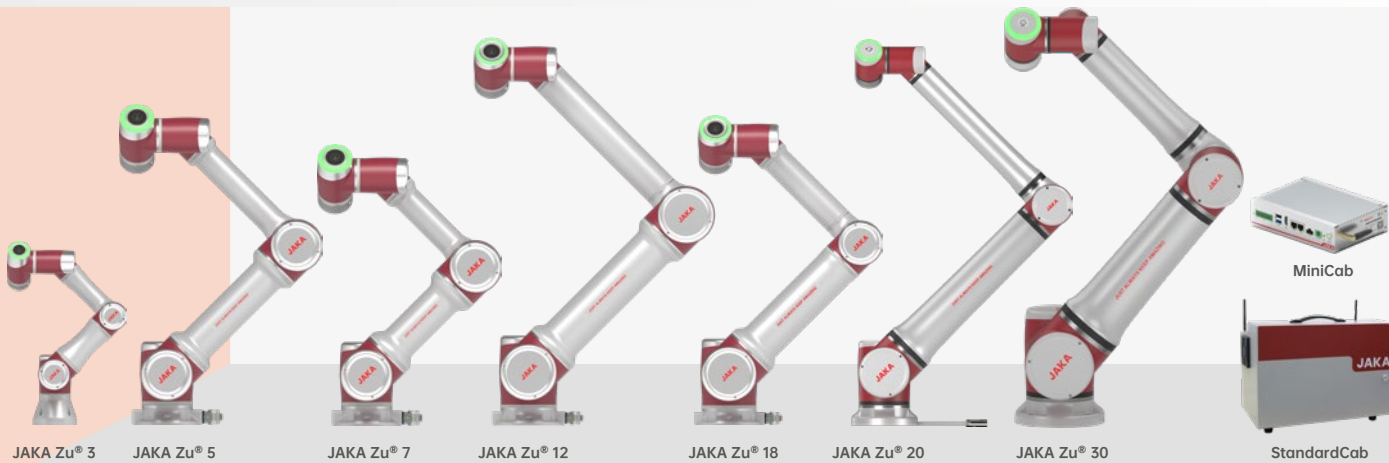
Ease of Use

Built-in torque feedback,
drag teaching, and
graphic programming for
easy use.



High Precision

Excellent repeatability,
accuracy, and an
MTBF of 80,000 hours.



Product features	Product parameters	JAKA Zu® 3		JAKA Zu® 5		JAKA Zu® 7		JAKA Zu® 12		JAKA Zu® 18		JAKA Zu® 20		JAKA Zu® 30	
	Maximum payload	3 kg		5 kg		7 kg		12 kg		18 kg		20 kg		30 kg	
	Weight	12 kg		23 kg		22 kg		41 kg		35 kg		68 kg		65 kg	
	Reach	626 mm		954 mm		819 mm		1327 mm		1073 mm		1780 mm		1350 mm	
	Accuracy	±0.02 mm		±0.02 mm		±0.02 mm		±0.03 mm		±0.03 mm		±0.05 mm		±0.05 mm	
	Number of axis	6		6		6		6		6		6		6	
	Programming	Drag teaching and graphic programming		Drag teaching and graphic programming		Drag teaching and graphic programming		Drag teaching and graphic programming		Drag teaching and graphic programming		Drag teaching and graphic programming		Drag teaching and graphic programming	
	Teach pendant	PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)	
Movement	Robot joint	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed
	Joint 1	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	120°/s	±360°	120°/s	±360°	120°/s	±360°	120°/s
	Joint 2	-85°, +265°	180°/s	-85°, +265°	180°/s	-85°, +265°	180°/s	-85°, +265°	120°/s	-85°, +265°	120°/s	-85°, +265°	120°/s	-85°, +265°	120°/s
	Joint 3	±175°	180°/s	±175°	180°/s	±175°	180°/s	±175°	120°/s	±175°	180°/s	±175°	120°/s	±175°	120°/s
	Joint 4	-85°, +265°	220°/s	-85°, +265°	180°/s	-85°, +265°	180°/s	-85°, +265°	180°/s	-85°, +265°	180°/s	-85°, +265°	220°/s	-85°, +265°	220°/s
	Joint 5	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	220°/s	±360°	220°/s
	Joint 6	±360°	220°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s	±360°	220°/s	±360°	220°/s
	Maximum linear speed	/	1.5 m/s	/	3 m/s	/	2.5 m/s	/	3 m/s	/	3.5 m/s	/	1.5 m/s	/	4.2 m/s
Specifications	Nominal power consumption	150 W		350 W		350 W		500 W		600 W		750 W		750 W	
	IP classification	IP54		IP54		IP54		IP54		IP54		IP65		IP65	
	Tool end I/O interface	Digital input 2		Digital input 2		Digital input 2		Digital input 2		Digital input 2		Digital input 2		Digital input 2	
		Digital output 2		Digital output 2		Digital output 2		Digital output 2		Digital output 2		Digital output 2		Digital output 2	
		Analog input 1		Analog input 1		Analog input 1		Analog input 1		Analog input 1		Analog input 1		Analog input 1	
	Base diameter	129 mm		158 mm		158 mm		188 mm		188 mm		246 mm		246 mm	
Electrical cabinet	IP classification	IP44		IP44		IP44		IP44		IP44		IP44		IP44	
	I/O ports	16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs	
	Communication	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP	
	Power	100-240 VAC, 50-60 Hz		100-240 VAC, 50-60 Hz		100-240 VAC, 50-60 Hz		100-240 VAC, 50-60 Hz		100-240 VAC, 50-60 Hz		100-240 VAC, 50-60 Hz		100-240 VAC, 50-60 Hz	
	Size	410×307×235 mm (W×H×D)		410×307×235 mm (W×H×D)		410×307×235 mm (W×H×D)		410×307×235 mm (W×H×D)		410×307×235 mm (W×H×D)		410×307×235 mm (W×H×D)		410×307×235 mm (W×H×D)	
	Weight	13.5 kg		15.4 kg		15.4 kg		18 kg		18 kg		18 kg		18 kg	

JAKA S

Improved Durability

IP65 rating for superior protection.

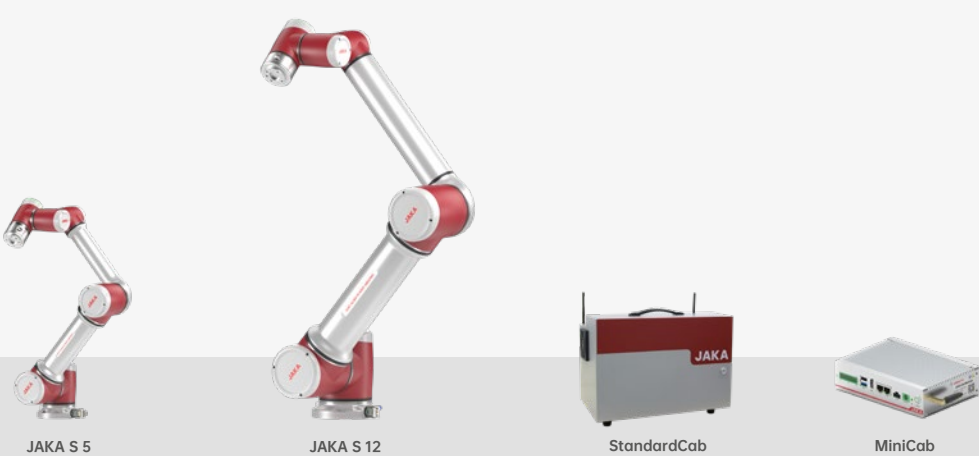
Precision Handling

Integrated force control for effortless operation.

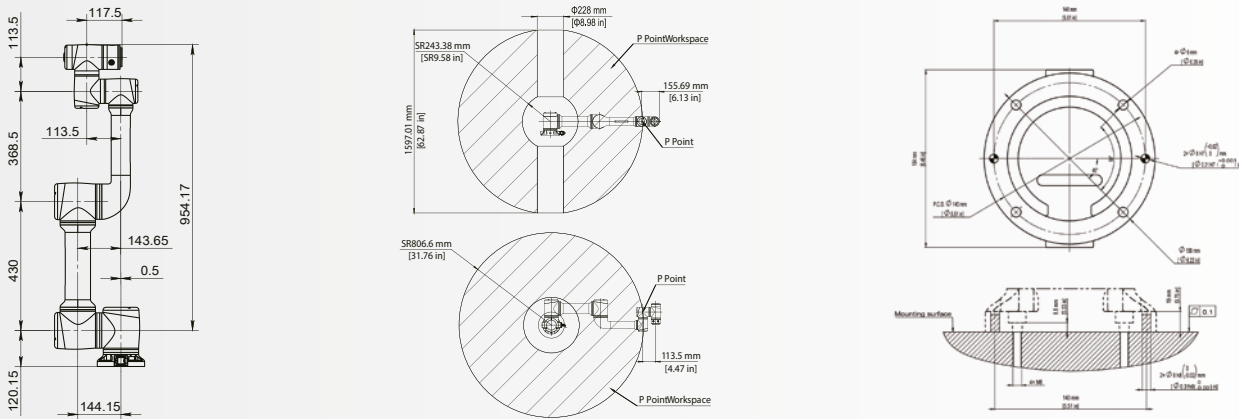
Easy Deployment

Instant access to force control at a glance.

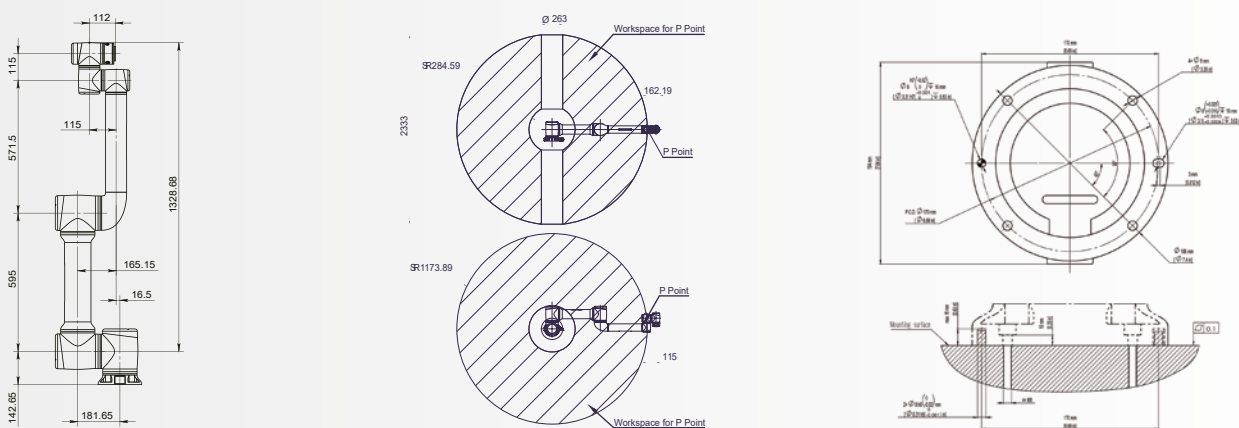
Product features	Product parameters	JAKA S 5		JAKA S 12	
	Maximum payload	5 kg		12 kg	
	Reach	954 mm		1327 mm	
	Number of axis	6		6	
	Nominal power consumption	350 w		500 w	
	Operational temperature	-10~50°C			
Force/torque sensor performance	Force/torque sensor	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z
	Measurement range	200 N	24 Nm	400 N	48 Nm
	Max force/torque limit	3000 N	300 Nm	3000 N	300 Nm
	Accuracy of maximum range	1% F.S.	1% F.S.	1% F.S.	1% F.S.
	Force/torque resolution	0.1 N	0.1 Nm	0.1 N	0.1 Nm
Movement	Typical TCP speed	1 m/s	/	1 m/s	/
	Accuracy	±0.02 mm	/	±0.03 mm	/
	Robot joint	Working range	Maximum speed	Working range	Maximum speed
	Joint 1	±360°	180°/s	±360°	120°/s
	Joint 2	-85°~ +265°	180°/s	-85°~ +265°	120°/s
	Joint 3	±175°	180°/s	±175°	120°/s
	Joint 4	-85°~+265°	180°/s	-85°~+265°	180°/s
	Joint 5	±360°	180°/s	±360°	180°/s
	Joint 6	±360°	180°/s	±360°	180°/s
Specifications	IP classification	IP 65		IP 65	
	Robot mounting angle	Any orientation		Any orientation	
	Base diameter	158 mm		188 mm	
	Materials	Aluminium, PC		Aluminium, PC	
	Robot connection cable length	6 m		6 m	
	Weight	23 kg		41 kg	
	Humidity	10~90% RH			



JAKA S 5 Drawings



JAKA S 12 Drawings



JAKA Pro



Robust Durability

IP68 protection for maximum durability — dust, oil, and water-resistant.



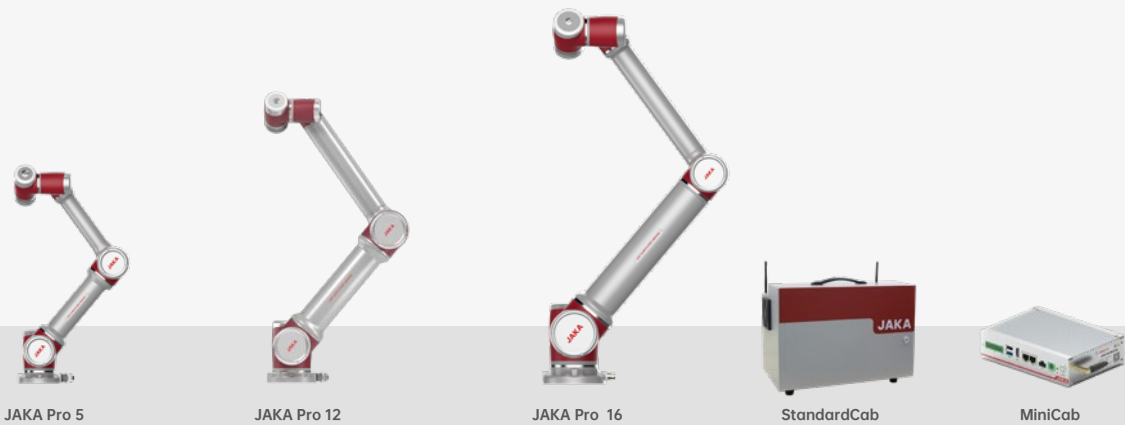
Steady Performance

±0.02 mm accuracy for reliable, 24/7 unsupervised operation.



Quick Deployment

Fast to deploy, easy to integrate and straightforward to reprogram.



Product features	Product parameters		JAKA Pro 5		JAKA Pro 12		JAKA Pro 16			
	Maximum payload		5 kg		12 kg		16 kg			
	Weight		23.5 kg		41 kg		74 kg			
	Reach		954 mm		1327 mm		1713 mm			
	Accuracy		±0.02 mm		±0.02 mm		±0.02 mm			
	Number of axis		6		6		6			
	Programming		Drag teaching and graphic programming		Drag teaching and graphic programming		Drag teaching and graphic programming			
	Teach pendant		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)		PC, mobile (PAD/mobile)			
Movement	Robot joint	Working range	Maximum speed		Working range	Maximum speed		Working range	Maximum speed	
	Joint 1	±360°	180°/s		±360°	120°/s		±360°	120°/s	
	Joint 2	-85°, +265°	180°/s		-85°, +265°	120°/s		-85°, +265°	120°/s	
	Joint 3	±175°	180°/s		±175°	120°/s		±175°	120°/s	
	Joint 4	-85°, +265°	180°/s		-85°, +265°	180°/s		-85°, +265°	180°/s	
	Joint 5	±360°	180°/s		±360°	180°/s		±360°	180°/s	
	Joint 6	±360°	180°/s		±360°	180°/s		±360°	180°/s	
	Maximum linear speed	/	3 m/s		/	3 m/s		/	3.9 m/s	
Specifications	Nominal power consumption		350 W		500 W		750 W			
	IP classification		IP68		IP68		IP68			
	Tool end I/O interface	Digital input 2		Digital input 2		Digital input 2				
		Digital output 2		Digital output 2		Digital output 2				
		Analog input 1		Analog input 1		Analog input 1				
	Base diameter		158 mm		188 mm		246 mm			
Electrical cabinet	IP classification		IP44		IP44		IP44			
	I/O ports		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs		16 digital inputs, 16 digital outputs, 2 analog inputs or outputs			
	Communication		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP		TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP			
	Power		100-240 VAC, 50-60 Hz		100-240 VAC, 50-60 Hz		100-240 VAC, 50-60 Hz			
	Size		410×307×235 mm (W×H×D)		410×307×235 mm (W×H×D)		410×307×235 mm (W×H×D)			
	Weight		15.4 kg		18 kg		18 kg			

JAKA Mini

Product description ↗

The JAKA Mini Series includes our most lightweight and compact collaborative robots, designed for quick setup and seamless integration into a wide range of work environments. They offer strong performance and flexibility with simple tools for customization.

With their small footprint, quiet operation, and sleek look, robots in the Mini Series are perfect for industries like education, retail, and services. Their budget-friendly design makes them an ideal entry point for businesses looking to start their automation journey.



Ideal for B2C



Cost-Effective



Lightweight





Weight
<10 kg



Payload
1-2 kg



Reach
580 mm



Accuracy
±0.1 mm



Application scenarios ↗



Product features	Product parameters	JAKA MiniCobo	JAKA Mini 2
	Maximum payload	1 kg	2 kg
	Weight (including cables)	9.4 kg	9.9 kg
	Reach	580 mm	580 mm
	Accuracy	±0.1 mm	±0.1 mm
	Number of axis	6	
	Programming	Drag teaching and graphic programming	
	Teach pendant	Mobile terminal (computer/pad/mobile phone)	
	Collaborative operation	Collaborative operation as ISO 10218-1: 2011	
Movement	Robot joint	Working range	
	Joint 1	±360°	
	Joint 2	±125°	
	Joint 3	±130°	
	Joint 4	±360°	
	Joint 5	±120°	
	Joint 6	±360°	
	Typical TCP speed	1 m/s	
Specifications	Nominal power consumption	150 W	180 W
	Rated voltage	24 VDC	48 VDC
	Operational temperature	0-50°C	0-50°C
	IP classification	IP40	IP40
	Robot mounting angle	Any orientation	
	Tool I/O interface	Digital input 2	
		Digital output 2	
		Analog input 2	
	Tool I/O power	24 VDC	
	Tool I/O size	M8	
	Materials	Aluminum, PC	
	Base diameter	124 mm	
	Cable length	6 m	
Electrical cabinet	Power input	20-60 VDC	
	I-Out	≤40 A	
	Size	180×128×47 mm (L×W×H)	
	IP classification	IP20	
	I/O	7 digital inputs: I/O configurable	
	I/O Power	24 VDC	
	Installation	Panel/Guide Rail	
	Communication	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP	
	Weight	1.1 kg	
	Materials	Aluminum, Steel	



JAKA Lens 2D



Flexible and Convenient

Vision system for easy adaptation to different scenarios.



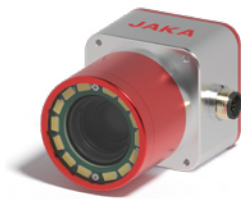
Customizable

Drag-and-drop programming with flexible function combinations for tailored inspections.



Easy Integration

Seamless software and hardware integration for quick and easy deployment.



Product description ▾

The JAKA Lens 2D is a high-resolution camera with adjustable lighting designed for clear 2D image capture. It allows real-time imaging with the flexibility to control the light source.

With features like automatic target recognition, visual positioning, and easy calibration, the system is simple to set up and operate for various image processing needs.

Lens 2D parameter	Lens 2D CGC500-F08	Lens 2D CGC500-F16
Resolution	2592×1944	2592×1944
Max frame rate	24 fps	24 fps
Data interface	GigE	GigE
Color mode	Black and white / color	Black and white / color
Lens focal length	8 mm	16 mm



JAKA Lens VPS



High Reliability

Effectively isolates external factors. Provides stable and consistent protection.



High Performance

Combines high-speed with large storage capacity. Features an embedded acceleration engine for enhanced performance.



High Convenience

No complex software installation required. Easily accessible through a standard web browser.



Product description ▾

The JAKA virtual protection system uses an industrial wide-angle camera and a vision system from JAKA and is directly connected to the cobot controller. The camera is placed above the robot's working area to monitor the working scene. If an external object (a person or a device) enters the monitoring area, the camera system detects the interference and sends instructions to the robot to take appropriate safety measures to ensure the safety of man and machine.

Lens VPS parameter	JAKA Lens Virtual Protection System
Resolution	820 w Pixel
Response time	200 ms
Installation height	2.5 m (suggested) GigE
Scope of protection area	5 m × 2,6 m (adjustable)
Installation mode	Directly above, side (any angle)



JAKA StandardCab



Seamless Integration

Meets the operational needs of full-load models.

Adaptable

Equipped with extensive I/O's and industrial communication interfaces.

Smart Connectivity

Integrated industrial multi-protocol control module.



Product description ▾

The JAKA StandardCab is a durable robot controller designed for seamless operation and communication with JAKA collaborative robots. It features an integrated wireless network module for mobile deployment and connectivity. Compatible with all JAKA cobots, it supports multiple device interfaces and industrial protocols, enabling integration with various equipment, including 3D vision systems, photoelectric sensors, conveyor belts, and laser scanners—offering a flexible and versatile automation solution.

Parameters	JAKA StandardCab
IP rating	IP44
IO Interfaces	16 digital inputs, 16 digital outputs, 2 analog inputs or outputs
Power supply (internal)	24 V
Communication	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP
Power supply	100-240 V AC, 50-60 Hz
Cabinet size	410×307×235 mm (W×H×D)
Weight	13 kg
Material	Plastic sprayed carbon steel plate



JAKA MiniCab



Space-Saving Design

Compact mini control cabinet for efficient use of space.



Wide Compatibility

Compatible with majority of JAKA collaborative robots.



Portable

Designed for easy transport and mobile use.



Product description ▾

The industry's smallest robot controller, weighing only 1.1 kg, supports a wide DC input power range, is compatible with various models and power loads, features an integrated wireless network module, and is ideal for mobile platforms like AGVs or industrial electrical cabinets.

Parameters	JAKA MiniCab
Input power / current	DC30-60 V / ≤40 A
Controller size	180×28×47 mm (L×W×H)
IP rating	IP20
IO Ports	7-way port; Input and output configurable
Power supply (internal)	DC 24 V
Installation method	Panel / guide rail
Communication	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP
Weight	About 1.7 kg (including accessories)
Material	Aluminum alloy, steel

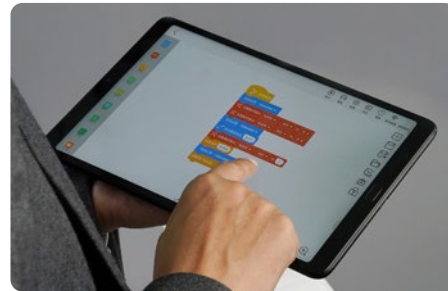
Flexible Programming of JAKA Robots

Whether you're a seasoned robotics engineer or new to automation, JAKA makes programming effortless and efficient. With numerous versatile programming options – ranging from intuitive drag-and-drop interfaces to advanced coding flexibility – we cater to diverse industries, applications, and skill levels. No matter your expertise, JAKA ensures a seamless programming experience, allowing you to focus on optimizing productivity.



JAKA Zu® App

The JAKA Zu App is our user-friendly programming platform based on the widely used programming language Scratch. Designed for simplicity, it allows users to program JAKA cobots through an intuitive drag-and-drop interface on tablets or smartphones.



- **Ideal For:** Beginners and operators with minimal programming experience.
- **Key Features:** Visual programming, real-time control, large variety of drag-and-drop commands.



Drag & Teach

With JAKA's direct teaching feature, users can simply guide the robot arm through desired movements to program tasks. This intuitive method reduces the learning curve and accelerates setup time.

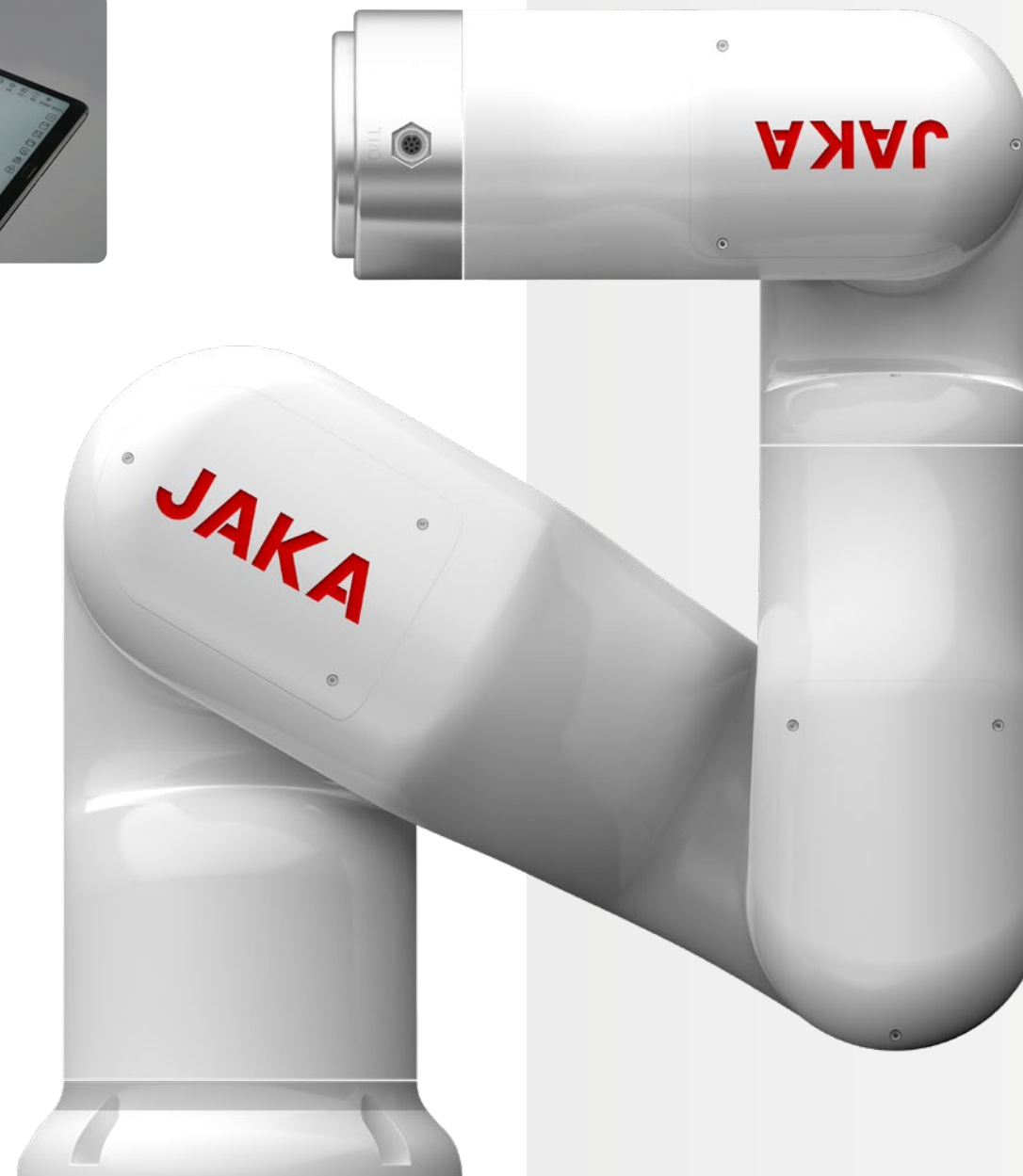
- **Ideal For:** Quick setups and repetitive tasks.
- **Key Features:** Effortless task recording with a few guided movements, no prior programming knowledge required



SRCI (Standard Robot Communication Interface)

SRCI enables seamless integration of JAKA cobots into PLC automation using standard Profinet protocols. It is designed for industries that require robust and reliable connectivity.

- **Ideal For:** Technicians with prior experience on SIMATIC hardware and software.
- **Key Features:** The use of SIMATIC Robot Integrator via TIA Portal.



TCP/IP

JAKA supports an external control protocol based on TCP/IP, offering a comprehensive set of interfaces that enable customers to control the robot and retrieve information.

- **Ideal For:** Programming environments with TCP server structure.
- **Key Features:** TCP server on the robot controller to receive specific commands and provide feedback status data.



JAKA SDK (Software Development Kit)

JAKA SDK is a comprehensive toolkit designed for developers and skilled system integrators to efficiently build applications for collaborative robots.

- **Ideal For:** Advanced users, software developers, and integrators.
- **Key Features:** The SDK communicates with the robot over TCP/IP and is available as a library for C/C++, C#, and Python.



Offline Programming

The JAKA Virtual Machine, along with third-party software like RoboDK, offers an efficient solution for programming without a physical robot: create, simulate, and test programs in a virtual environment before deployment.

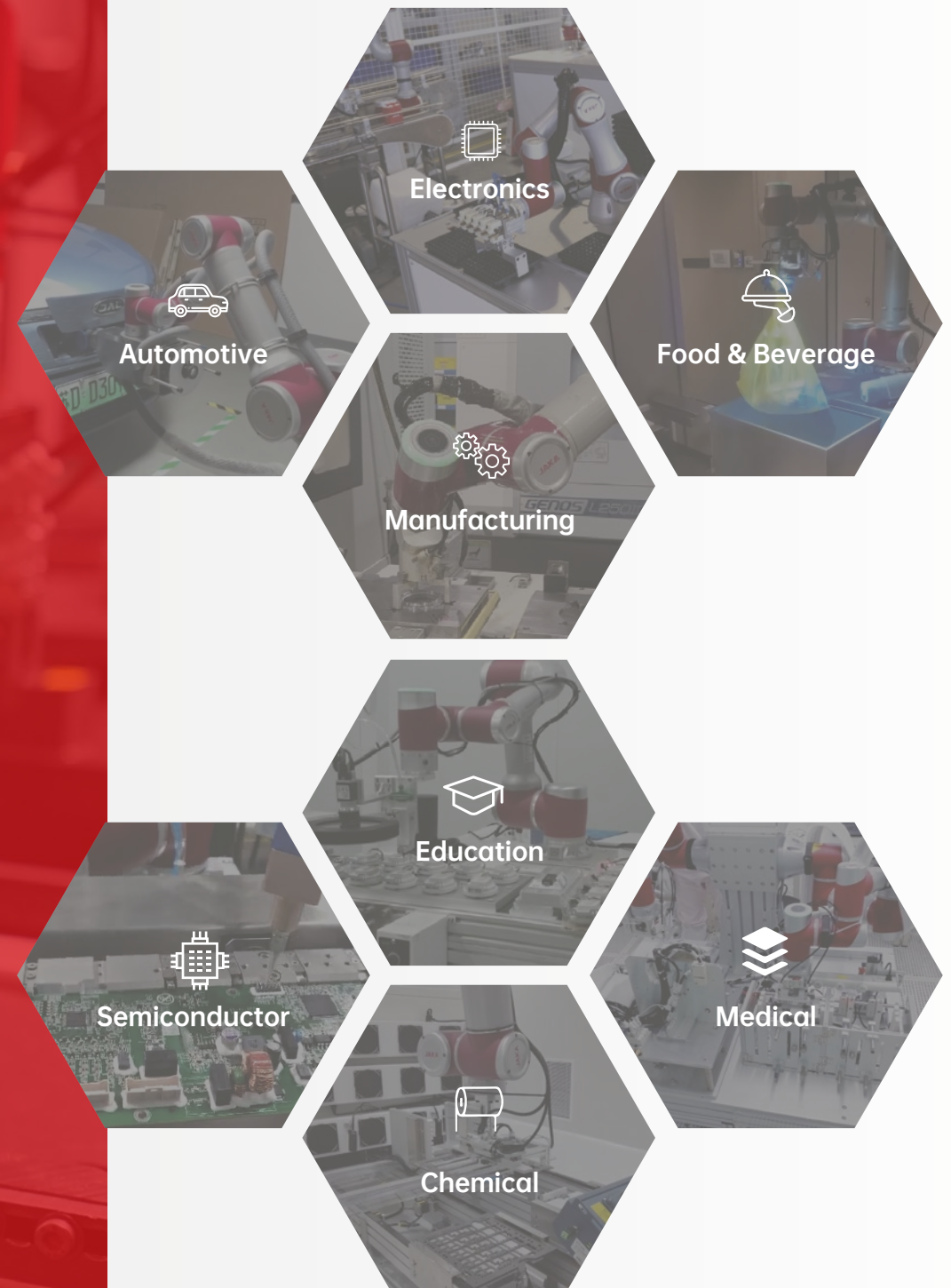
- **Ideal For:** Environments where downtime must be minimized, or where a physical connection to the robot is unavailable, such as training and education settings.
- **Key Features:** Connect the JAKA Zu® App to the virtual machine using an IP address. The virtual machine can also be operated through TCP/IP and the JAKA SDK, with these functions also available via third-party software.

JAKA

Key Industries



Automotive
Electronics
Semiconductor
Manufacturing
Medical
Food & Beverage
Chemical
Renewable Energy
Education
Agriculture



Automotive Industry

Dust removal from lighting covers



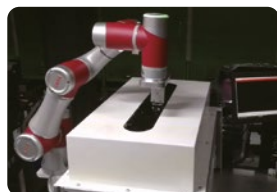
Screwing in lighting assemblies



BEV automatic charging station



Lighting strip quality control



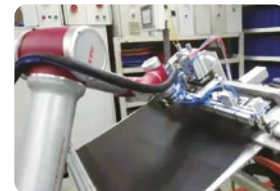
Screwing in powertrain assemblies



Electric drivetrain wire winding



Automotive blind riveting



Belt tension inspection



Battery pack spraying operations



Transmission housing handling



Screwing in seat assemblies



Machine tending for stamped parts



Mirror quality control inspection



Handling operations for shelves



Machine tending for exhaust systems



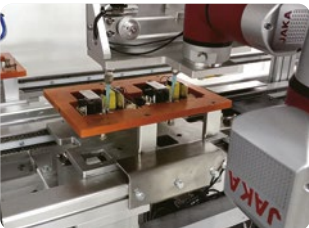
Machine tending operations for suspension parts



Electronics / Semiconductor Industry



CNC Machine tending with AGV/Robot



Power module coating



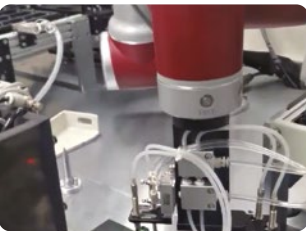
Scanning and inspection of battery packs



Soldering



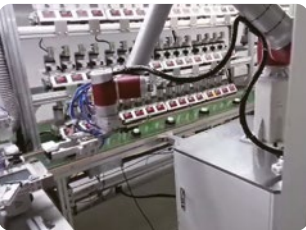
Quality inspection of PCB boards



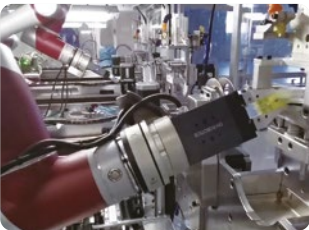
Visual inspection on smartphones



Buzzer detection



Handling operations during product assembly



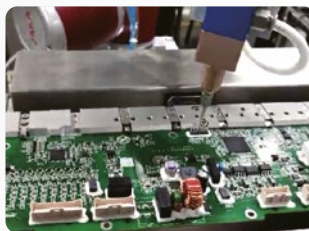
Glue residue removal in earbuds



Quality inspection for smartwatches



Quality inspection for semiconductor parts



Gluing operations on PCB boards



Laser etching for electronics



Screwing operations on lamp assembly



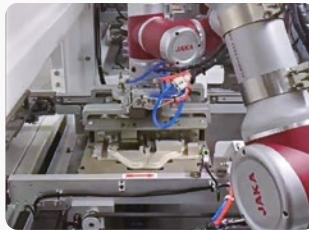
Assembly with dual arms



Blanking operations on PCBs



Sandblast cleaning operations



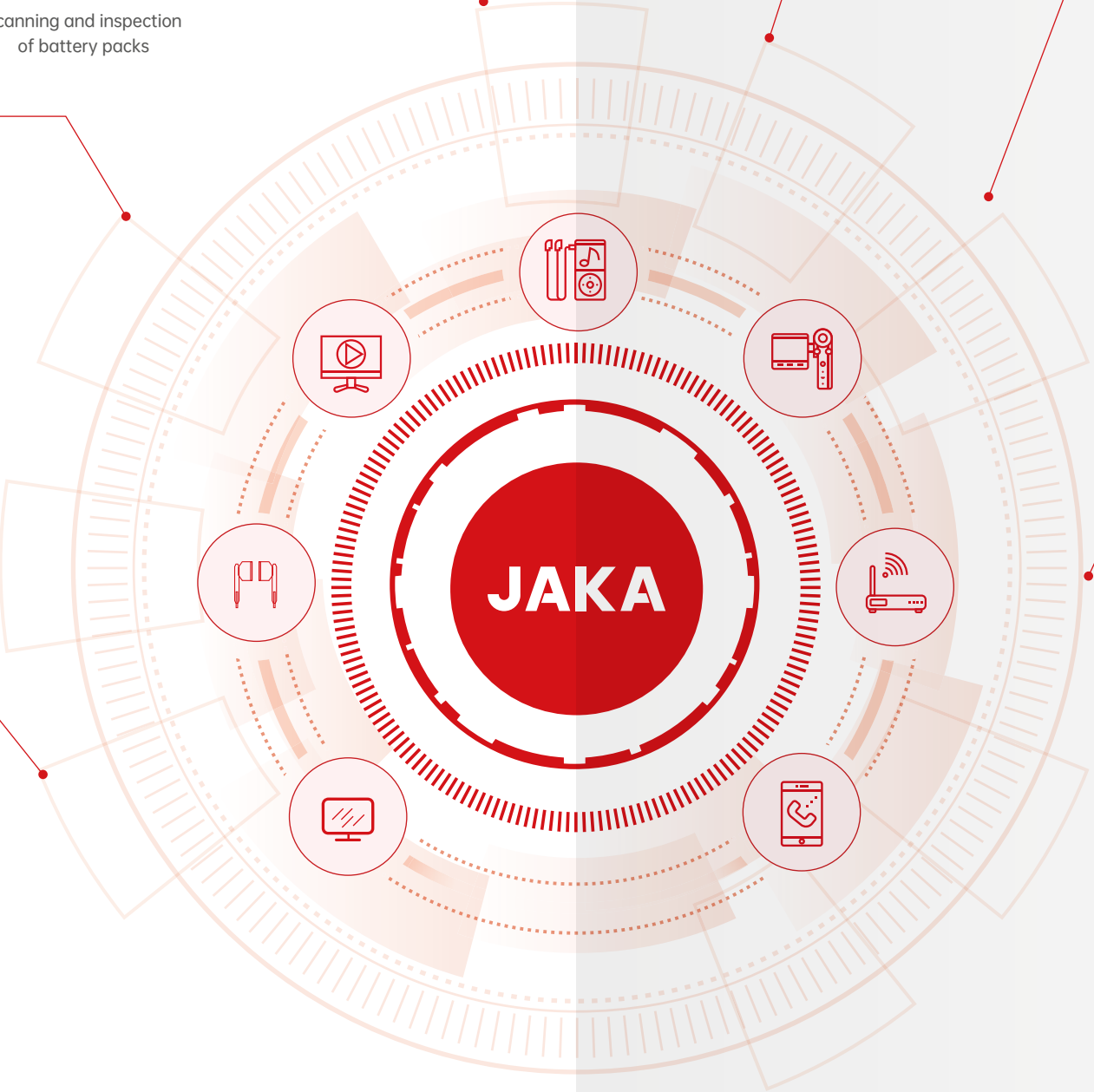
Protective film removal



Gluing operations on PCs

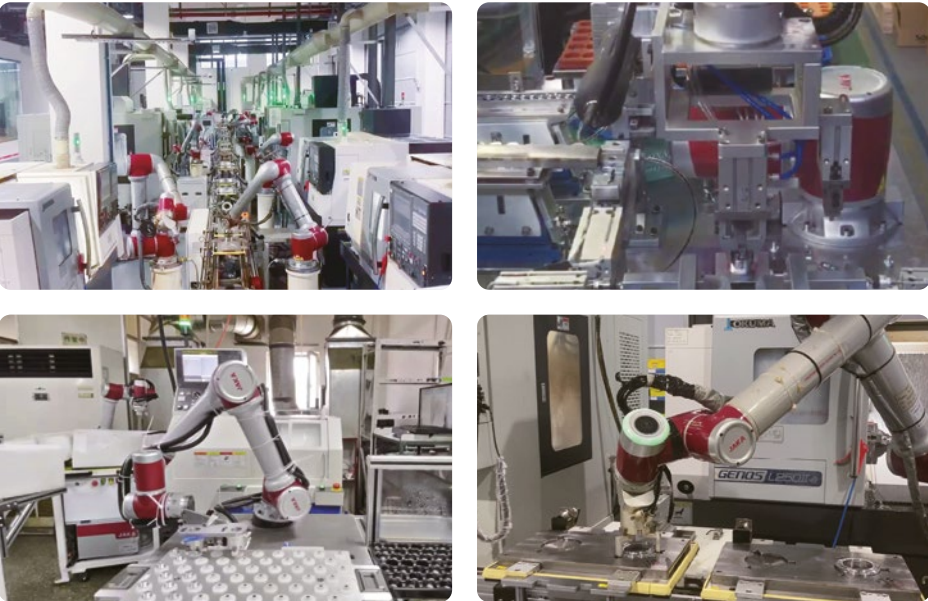


Handling operation on PCB boards

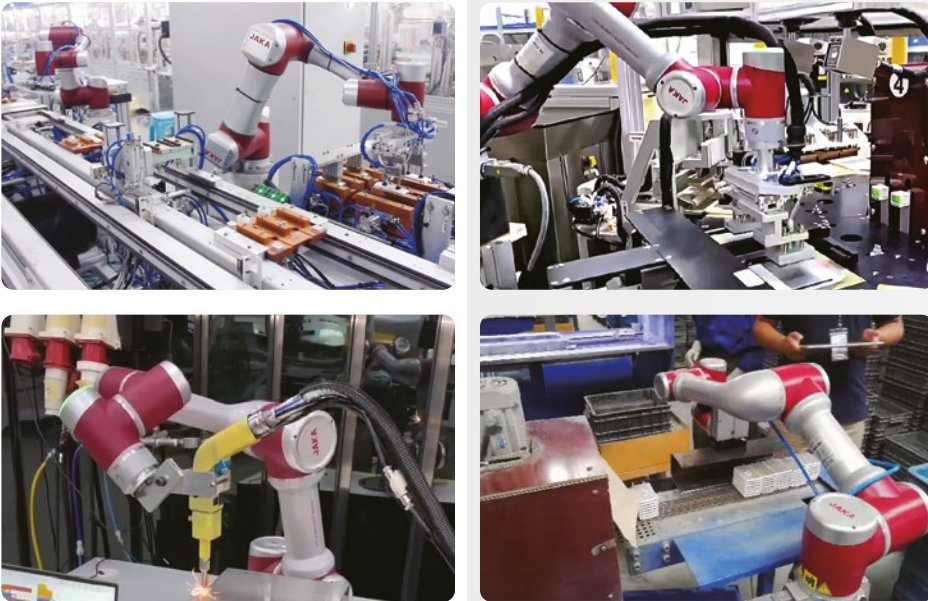


Other Industrial and Commercial Sectors

Manufacturing



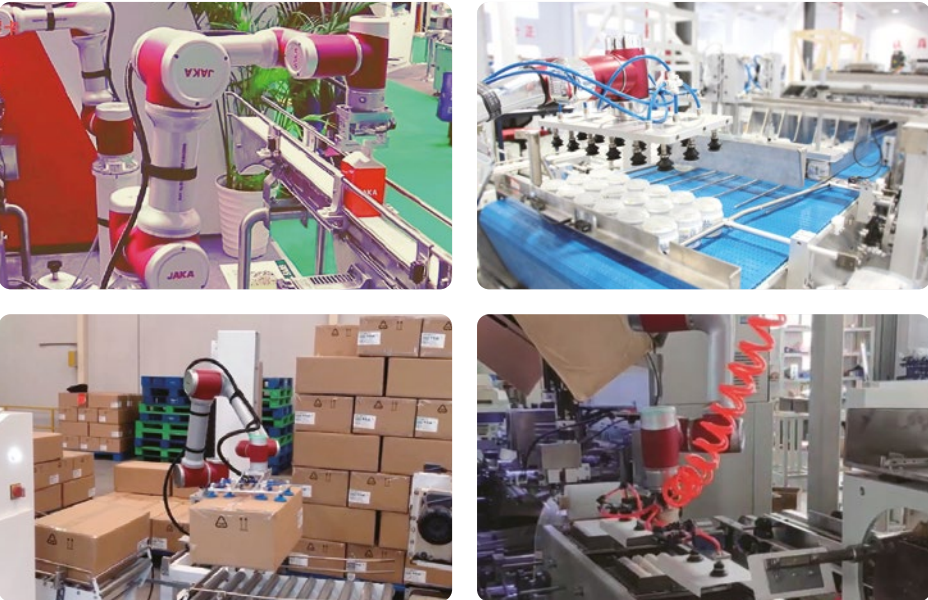
Renewable Energy



Electrical Appliances



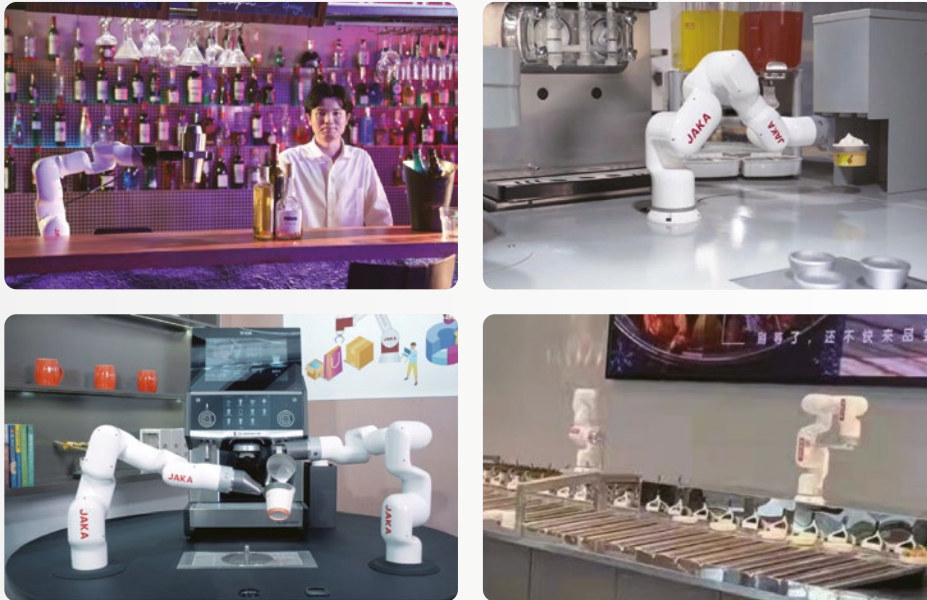
Food & Beverage



Medical



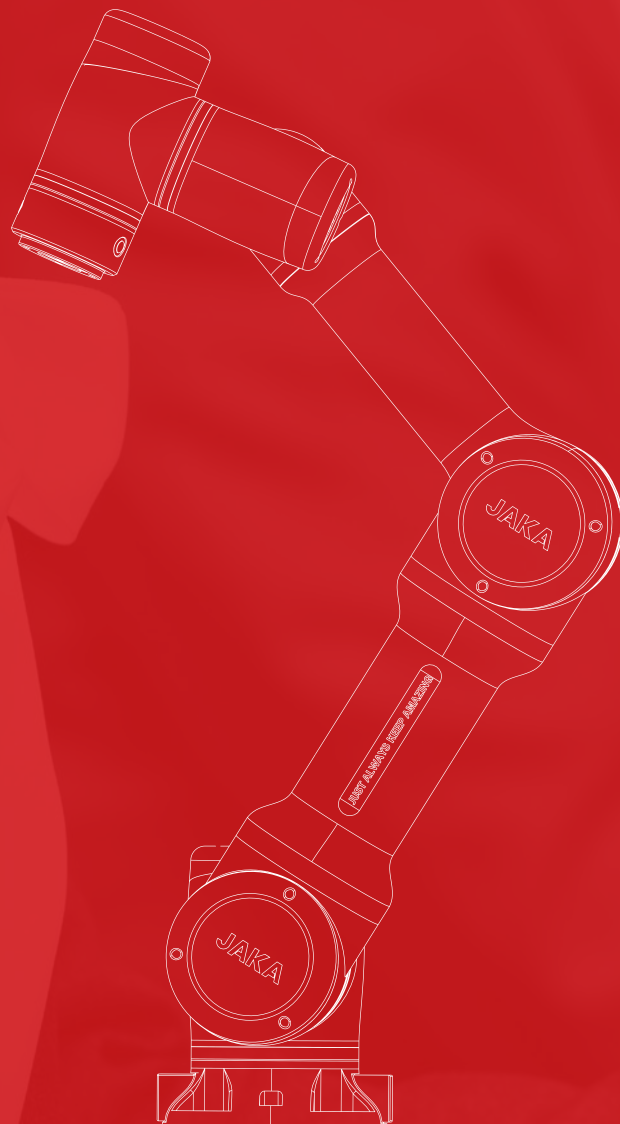
Hospitality





JAKA

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24/7 online support



Professional technical support



Digital solutions



Full service tracking



High-level industry training

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